

Cross-walking Three-Axis/Five-Axis Servo Driven Robots



注塑用机械手 TAKE-OUT ROBOT

ME WE - 120 ME WE - 120s

STANDARD FUNCTION

256
Packaging motion Max. 256 points

- 115 x 2

Free packaging motion 115points × 2stage

Forward and rotate at removing side

Posture control during traverse

Posture midway descent at release side

E jector link

Defective product reject circuit

Initial defective product reject circuit

Delayed arm descent

Midway runner release Move Revert

Runner release within mold

Additional vacuum sensing unit 2 circui

Delayed traverse

Undercut extract circuit

Start signal of conveyor

nternal memory for Max 100 molds

Lock function of setting value

Extraction from fixed mold

2

Two language exchange Chinese Ænglish

UNIT MEWE - 120 MEWE - 120:



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